

Online Learning and Perceptron Mistake Bound

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Reading: Mitchell Chapter 7.5
Cristianini/Shawe-Taylor Chapter 2-2.1.1

Online Learning Model

- Initialize hypothesis $h \in H$
- FOR i from 1 to infinity
 - Receive x_i
 - Make prediction $\hat{y}_i = h(x_i)$
 - Receive true label y_i
 - Record if prediction was correct (e.g., $\hat{y}_i = y_i$)
 - Update h

(Online) Perceptron Algorithm

- Input: $S = ((\vec{x}_1, y_1), \dots, (\vec{x}_n, y_n))$, $\vec{x}_i \in \mathbb{R}^N$, $y_i \in \{-1, 1\}$
- Algorithm:
 - $\vec{w}_0 = \vec{0}$, $k = 0$
 - FOR $i=1$ TO n
 - * IF $y_i(\vec{w}_k \cdot \vec{x}_i) \leq 0$ ### makes mistake
 - $\vec{w}_{k+1} = \vec{w}_k + y_i \vec{x}_i$
 - $k = k + 1$
 - * ENDIF
 - ENDFOR
- Output: \vec{w}_k

Perceptron Mistake Bound

Theorem: For any sequence of training examples $S = ((\vec{x}_1, y_1), \dots, (\vec{x}_n, y_n))$ with

$$R = \max \|\vec{x}_i\| ,$$

if there exists a weight vector \vec{w}_{opt} with $\|\vec{w}_{opt}\| = 1$ and

$$y_i (\vec{w}_{opt} \cdot \vec{x}_i) \geq \delta$$

for all $1 \leq i \leq n$, then the Perceptron makes at most

$$\frac{R^2}{\delta^2}$$

errors.

Margin of a Linear Classifier

Definition: For a linear classifier h_w , the **margin** δ of an example (\vec{x}, y) with $\vec{x} \in \mathbb{R}^N$ and $y \in \{-1, +1\}$ is $\delta = y(\vec{w} \cdot \vec{x})$.

Definition: The margin is called **geometric margin**, if $\|\vec{w}\| = 1$. For general \vec{w} , the term **functional margin** is used to indicate that the norm of \vec{w} is not necessarily 1.

Definition: The (hard) margin of an unbiased linear classifier $h_{\vec{w}}$ on a sample S is $\delta = \min_{(\vec{x}, y) \in S} y(\vec{w} \cdot \vec{x})$.

Definition: The (hard) margin of an unbiased linear classifier $h_{\vec{w}}$ on a task $P(X, Y)$ is

$$\delta = \inf_{S \sim P(X, Y)} \min_{(\vec{x}, y) \in S} y(\vec{w} \cdot \vec{x}).$$